

Qualifying Exam (May 2022): Operations Research

You have 4 hours to do this exam. **Reminder:** This exam is closed notes and closed books.

Do 2 out of problems 1,2,3.

Do 2 out of problems 4,5,6.

Do 3 out of problems 7,8,9,10

All problems are weighted equally. On this cover page write which seven problems you want graded.

problems to be graded:

Academic integrity is expected of all students at all times, whether in the presence or absence of members of the faculty. Understanding this, I declare that I shall not give, use, or receive unauthorized aid in this examination.

Name (PRINT CLEARLY), ID number

Signature

(1). Consider the following LP problem and its optimal final tableau shown below:

$$\begin{aligned}
 \max z &= 2x_1 + x_2 - x_3 \\
 \text{s.t.} \quad &x_1 + 2x_2 + x_3 \leq 8 \\
 &-x_1 + x_2 - 2x_3 \leq 4 \\
 &x_1, x_2, x_3 \geq 0
 \end{aligned}$$

Final Tableau:

z	x_1	x_2	x_3	x_4	x_5	RHS
1	0	3	3	2	0	16
0	1	2	1	1	0	8
0	0	3	-1	1	1	12

- Write the dual problem and give the optimal dual variable values from the foregoing tableau.
- Using sensitivity analysis find a new optimal solution if the coefficient of x_2 in the objective function is changed from 1 to 3.
- Suppose that the following constraint is added to the problem:
 $x_2 + 2x_3 = 3$. Using sensitivity analysis find the new optimal solution.
- If you were to choose between increasing the right-hand-side of the first and second constraints, which one would you choose? Why? What is the effect of this increase on the optimal value of the objective function?
- Suppose that a new activity x_6 is proposed with unit return 6 and consumption vector $\mathbf{a}_6 = (2, 1)^t$. Find a new optimal solution. Is the new activity worth considering?

(2). Consider the assignment problem shown in the following table (rows: tasks; columns: individuals):

	Individual		
Task	1	2	3
1	17	18	16
2	14	19	17
3	15	19	18

- Write the linear programming formulation of this problem.
- Write the dual of the linear program formulated in part (a). List the complementary slackness conditions.
- Using the Hungarian algorithm, find an optimal primal and an optimal dual solution.
- Show that the optimal primal and dual solutions found in part (c) satisfy primal feasibility, dual feasibility and complementary slackness.

(3).

(a) Prove that the system of inequalities $A\mathbf{x} \leq \mathbf{b}$ has a solution \mathbf{x} iff (if and only if) there exists no nonnegative vector \mathbf{y} such that $\mathbf{y}^T A = 0$ with $\mathbf{y}^T \mathbf{b} < 0$.

(b) Use part (a) to prove that the system

$$\begin{aligned} -2x_1 + 3x_2 &\leq -2 \\ 3x_1 - x_2 &\leq 2 \\ -11x_1 - x_2 &\leq -7 \end{aligned}$$

has no solution.

(4). Consider a street with two lanes. Cars pass through lane i according to a Poisson process with rate λ_i , $i = 1, 2$. Assume that these two Poisson processes are independent. A woman who wants to cross the street need a seconds to cross lane 1 and b seconds to cross lane 2. Let T be the first time at which the woman could successfully cross the street (both lanes) in one go. Compute $E[T]$.

(5). Let $\{X(t), t \geq 0\}$ be a CTMC with stationary distribution π . Let $\{N(t), t \geq 0\}$ be a Poisson process with intensity λ that is independent of $\{X(t)\}$. Denote by S_n the time of the occurrence of the n th event in $\{N(t)\}$. Define $Y_n = X(S_n^+)$, i.e., the value of the CTMC immediately after the time of the n th event in $\{N(t)\}$. Show that $\{Y_n, n = 0, 1, \dots\}$ is a discrete-time Markov chain and find its stationary distribution.

(6). Consider a single server queue with an FCFS service discipline. Customers arrive according to a Poisson process with rate λ . The service times are i.i.d. exponentially distribution with parameter μ . An arriving customer who sees n customers in system will only join the system with probability $(n+1)/(n+2)$. (1) State the stability condition for the queueing system. (2) Assuming that the system is stable, compute the long run expected time a customer spends in the waiting line (not including service time).

(7). Suppose real-valued $(X_n)_{n \geq 1}$ have distribution functions F_n , and that $X_n \xrightarrow{\mathcal{D}} X$. Let $p > 0$ and show that for every positive N ,

$$\int_{-N}^N 1_{\{-N < x < N\}} |x|^p F(dx) \leq \limsup_{n \rightarrow \infty} \int_{-N}^N 1_{\{-N < x < N\}} |x|^p F_n(dx) < \infty,$$

where F is the distribution of X .

(8). Let T be a stopping time. For $A \in \mathcal{F}_T$, define

$$T_A(\omega) = \begin{cases} T(\omega) & \text{if } \omega \in A; \\ \infty & \text{otherwise.} \end{cases} \quad (1)$$

Show that T_A is a stopping time.

(9). (a). How efficiently (in big-Oh notation) can the (Euclidean) Delaunay diagram be constructed for n points in the plane? What about for n points in 3D? Describe briefly (without giving details) one method that achieves the time bound in 2D.

(b). For n distinct points in the plane (in any positions, degenerate or not) what is the fewest number of edges possible in the Delaunay diagram? Explain. What is the most number of edges possible in the Delaunay diagram? Explain.

(c). Let $S = \{p_1, p_2, \dots, p_n\}$ be a set of n points in the plane. Suppose we want only to determine whether or not the pair (p_1, p_2) defines a Delaunay edge. Describe how this can be done efficiently and state the running time.

(d). Let $S = \{p_1, p_2, \dots, p_n\}$ be a set of n points in the plane. Suppose we want only to determine whether or not the point p_1 is a vertex of the furthest site Delaunay diagram. How efficiently can this be done? Justify briefly.

(e). When the Fortune sweep algorithm is applied to a set of n points in the plane, what is kept stored in the sweep line status (SLS)? Describe briefly, but clearly.

(10). Consider the randomized incremental method for solving a 2-variable linear program. (Assume the objective function is to find the lowest (min- y) point in the intersection of the n halfplanes, $\{h_1, \dots, h_n\}$.)

(a). At certain stages of the algorithm, we are sometimes required to solve a one-dimensional LP. Draw an example of a case in which the addition of the i th constraint (halfspace h_i) requires the solution of a one-dimensional LP; give also an example of a case in which the addition of h_i does not require the solution of a one-dimensional LP. How does the algorithm tell which case occurs? (i.e., what test is done on each h_i ?)

(b). Describe briefly *what* a “one-dimensional LP” problem is, how it is defined in terms of the added constraint h_i , and how it is solved. What is the running time of the solution method? (in big-Oh notation)

(c). What is the probability that, during the solution of a 2-variable LP, we are required to solve a one-dimensional LP upon insertion of halfplane (constraint) h_i (the i th constraint inserted during the algorithm)? Why? (give a brief justification)

(d). We have seen various randomized incremental algorithms, in addition to 2-variable LP. State one such result. You need not describe the algorithm, just state what it solves, and what its expected running time is.